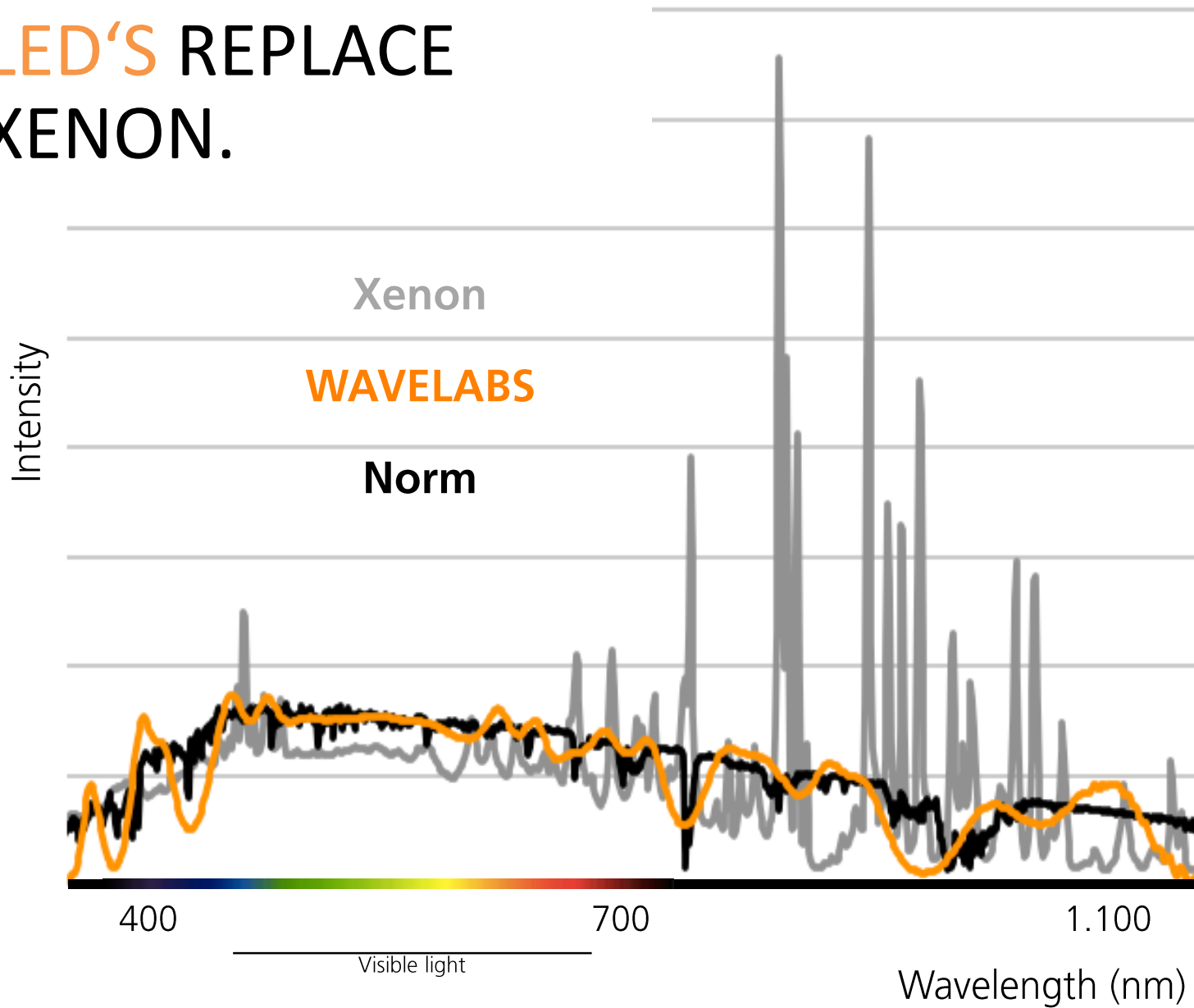


# Avoiding Errors in Fill-factor Measurements

Sascha Esefelder, Wavelabs

# LED'S REPLACE XENON.



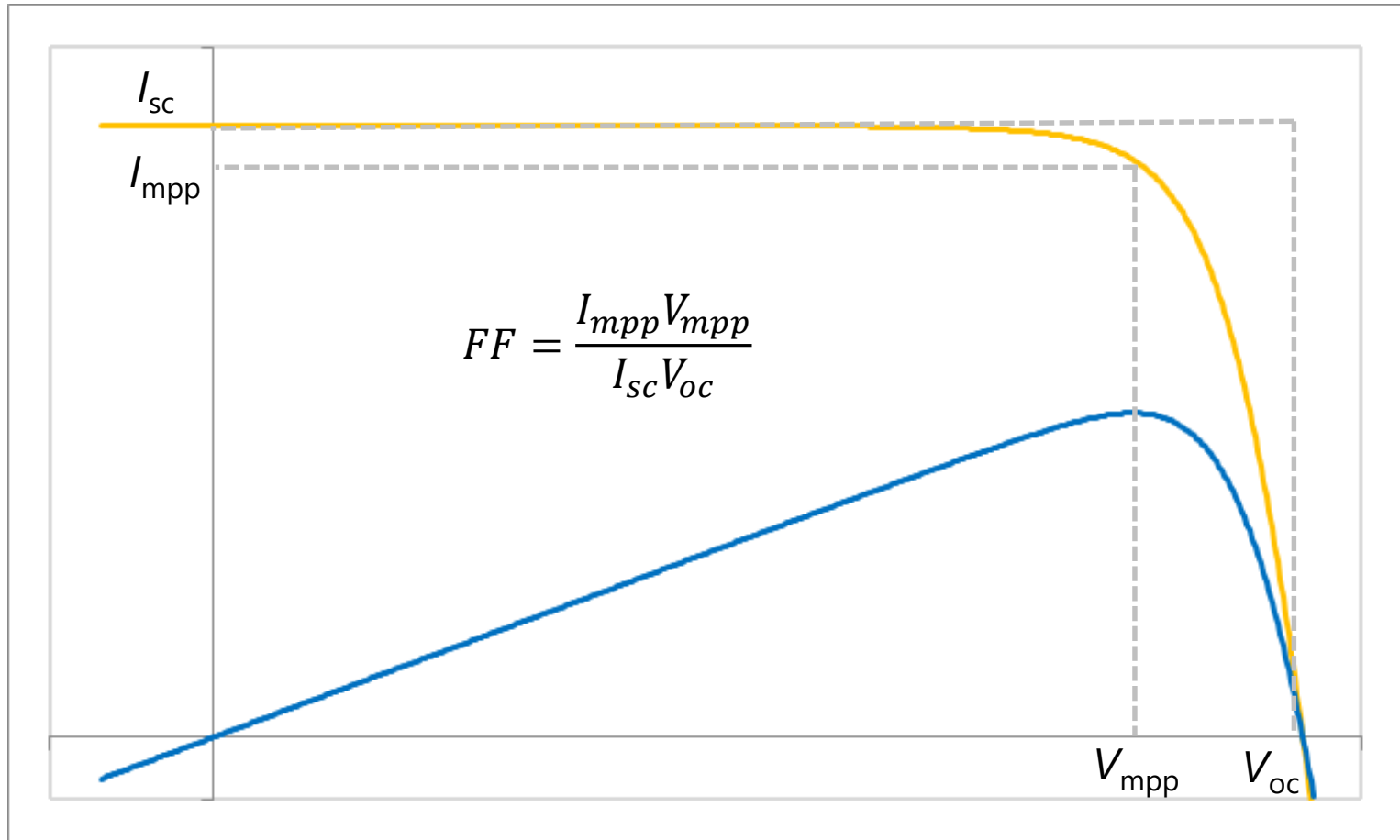
# LED'S GET REFERENCES.



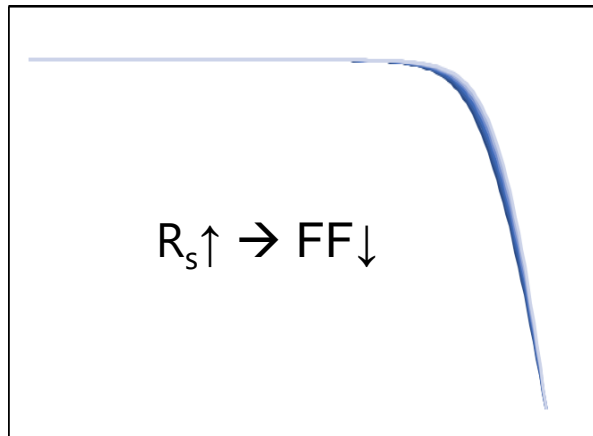
# Outline

- 1) Introduction
- 2) Ensuring STC conditions
- 3) Nonuniform contact resistance
- 4) Design of the contact bar
- 5) Conclusion

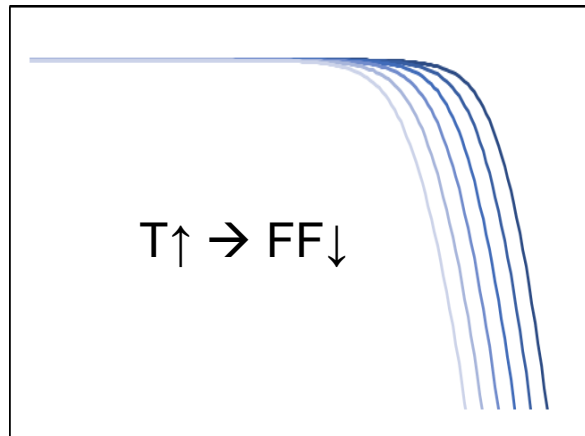
# Introduction



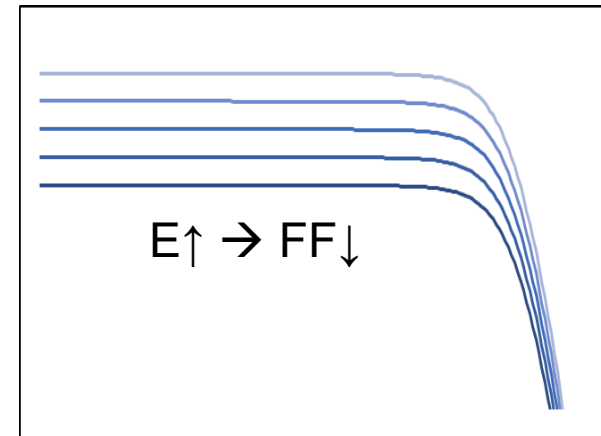
# Ensuring STC conditions



Laboratory



Production



- 4 point contacting
- Measurement at 25 °C
- Measurement at 1000W/m<sup>2</sup> including a spectral mismatch correction, shading correction
- ...

- 4 point contacting
- proper calibration on  $V_{oc}$  and knowledge of temperature coefficients
- proper calibration on  $I_{sc}$  (spectral match between production cell and reference cell)

# Nonuniform contact resistance

**Table III:** Simulated fill factors for measurement schemes with different load contacting and sensing.

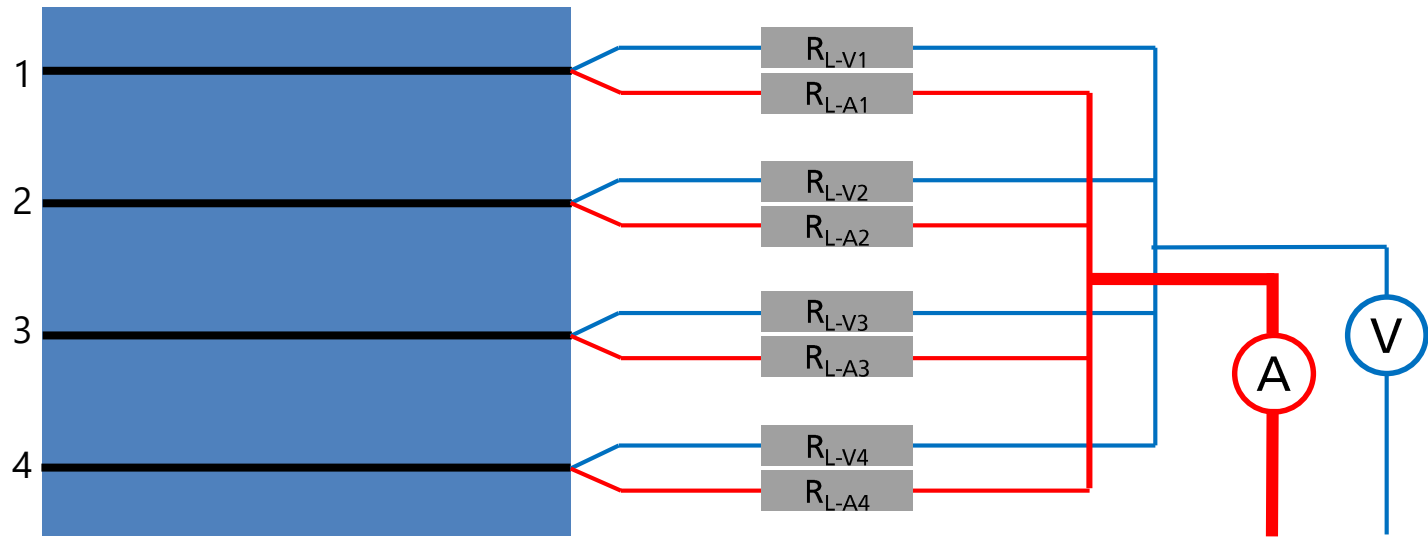
Load contacting scheme	$FF_1 / \%$ with $V_{BB1}$	$FF_2 / \%$ with $V_{BB2}$	$FF / \%$ with all BB
Ideal	78.50	78.50	78.50
I	76.99	79.81	77.92
II	66.55	82.11	70.35
III	78.56	78.47	78.53

Geisemeyer et. Al, 29th EUPVSEC 2014, 2BV.8.29

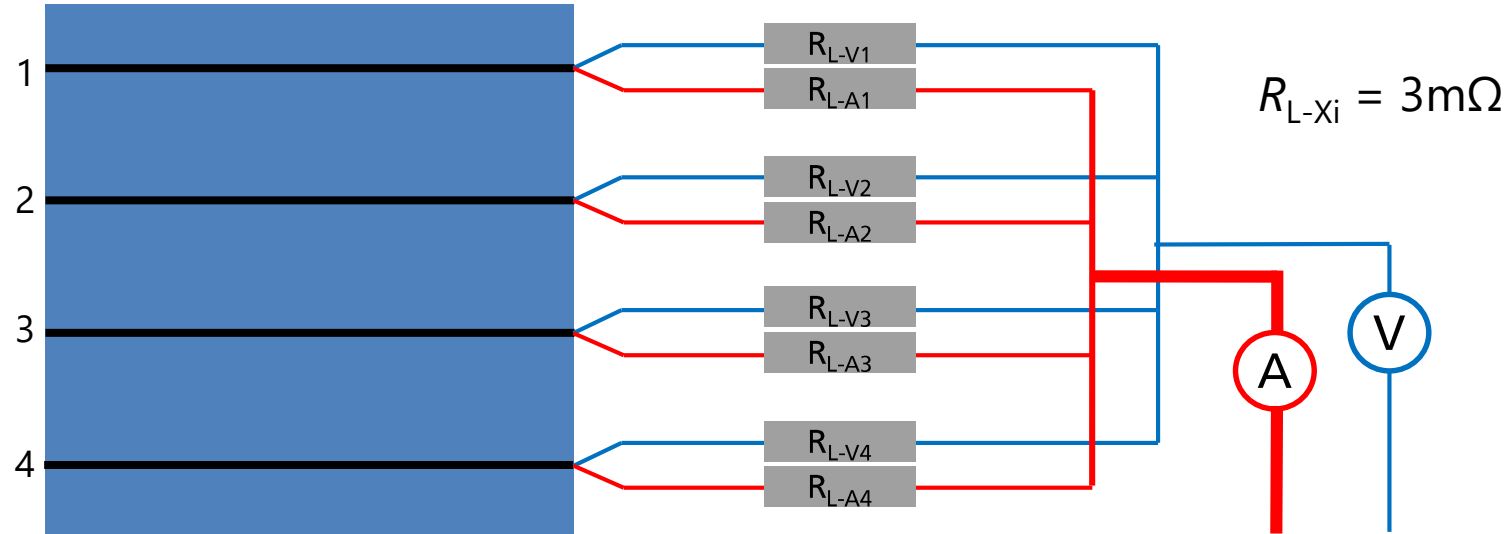
## Four terminal sensing

„Separation of current and voltage electrodes eliminates the lead and contact resistance from the measurement. “

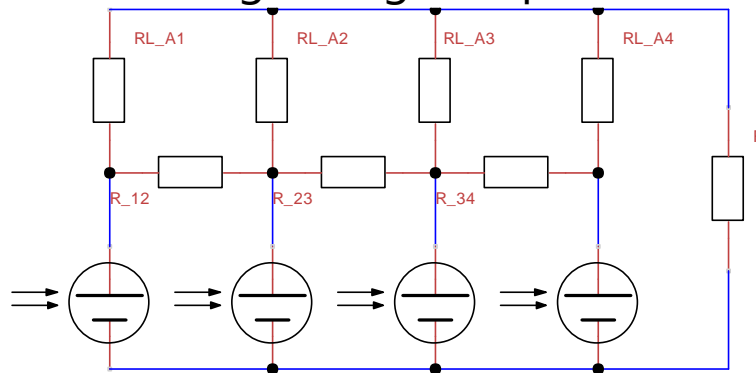
Wikipedia.org



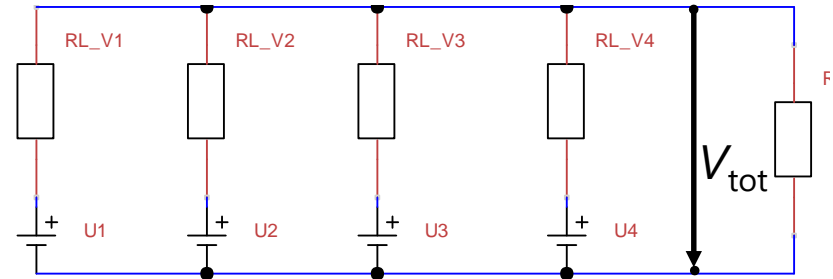
# Nonuniform contact resistance – Analytical model



1) Calculate the current flow and resulting voltage drops

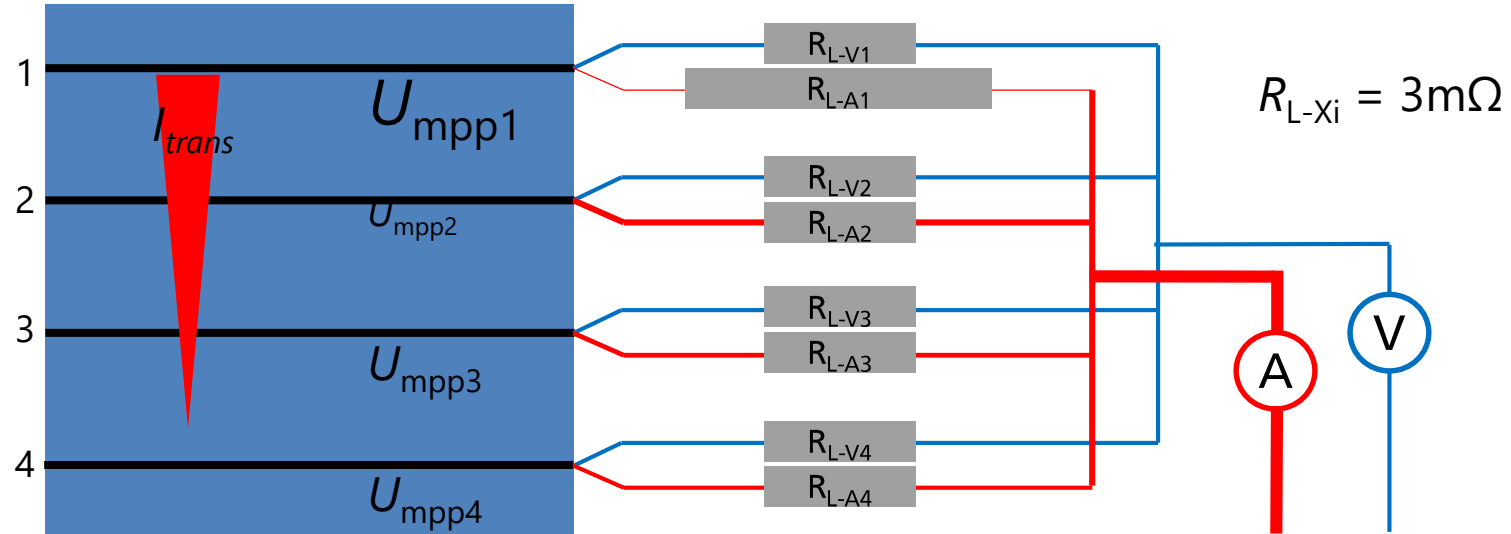


2) Calculate  $V_{\text{tot}}$





# Nonuniform contact resistance – Analytical model



$$\Delta U_{BB1-2} = I_{trans} * R_{BB1-2}$$

$$R_{L-A1} = 13m\Omega \rightarrow I_{trans} = 0.6A, \Delta U_{BB1-2} = 12 \text{ mV} \text{ für } R_{BB1-2} = 20m\Omega$$

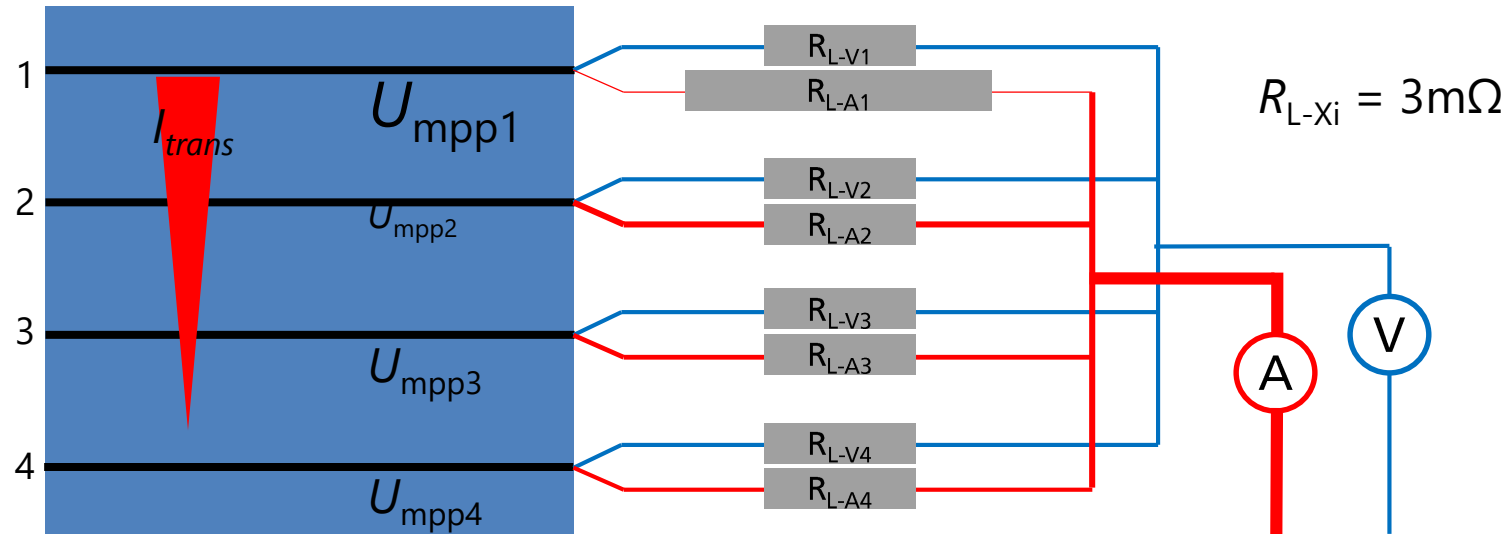
$$U_{mpp1} \neq U_{mpp2}$$

$$U_{mpp1} = U_{mpp3} + 6 \text{ mV}, U_{mpp2} = U_{mpp3} - 6 \text{ mV}$$

$$U_{mpp} = 1/4 \sum U_{mppi}$$

$$U_{mpp}(R_{L-Ai} \neq \text{const}) = U_{mpp}(R_{L-Ai} = \text{const}) \quad \text{Only for } R_{L-Vi} = \text{const}$$

# Nonuniform contact resistance – Analytical model



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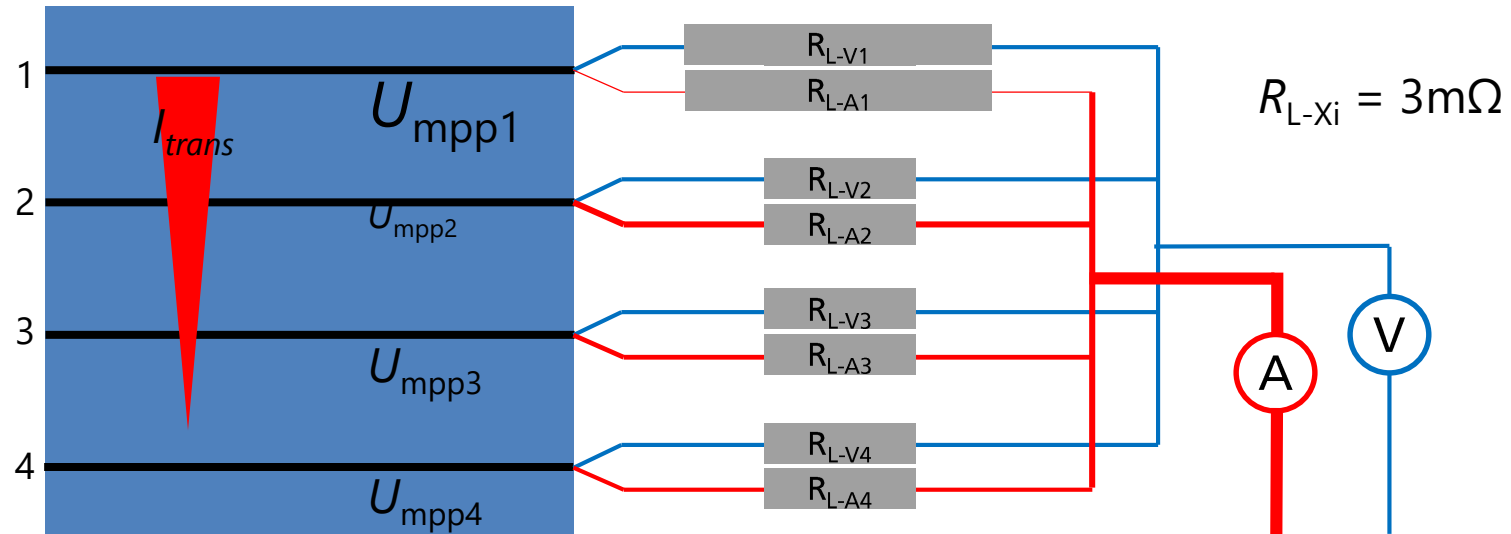
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$R_{L-V1-4}$	LLLL					
$\Delta U_{mpp} [\%] *$	0.0					

L = 3mΩ, H = 13mΩ

# Nonuniform contact resistance – Analytical model



$$\Delta U_{BB1-2} = I_{trans} * R_{BB1-2}$$

$$R_{L-A1} = 13m\Omega \rightarrow I_{trans} = 0.6A, \Delta U_{BB1-2} = 12 mV \text{ für } R_{BB1-2} = 20m\Omega$$

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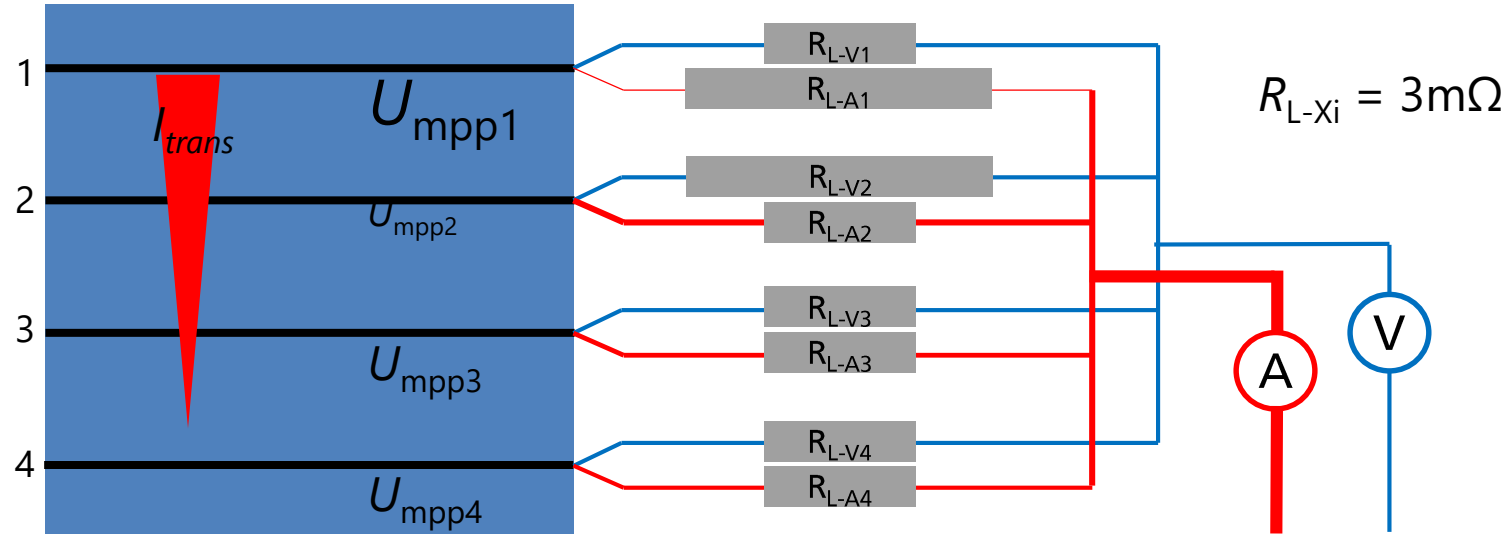
$$U_{mpp} = 1/4 \sum U_{mppi}$$

$$U_{mpp}(R_{L-Ai} \neq const) = U_{mpp}(R_{L-Ai} = const) \quad \text{Only for } R_{L-Vi} = const$$

$R_{L-V1-4}$	LLLL	HLLL				
$\Delta U_{mpp} [\%] *$	0.0	-0.26				

L = 3mΩ, H = 13mΩ

# Nonuniform contact resistance – Analytical model



$$\Delta U_{BB1-2} = I_{trans} * R_{BB1-2}$$

$$R_{L-A1} = 13m\Omega \rightarrow I_{trans} = 0.6A, \Delta U_{BB1-2} = 12 \text{ mV} \text{ für } R_{BB1-2} = 20m\Omega$$

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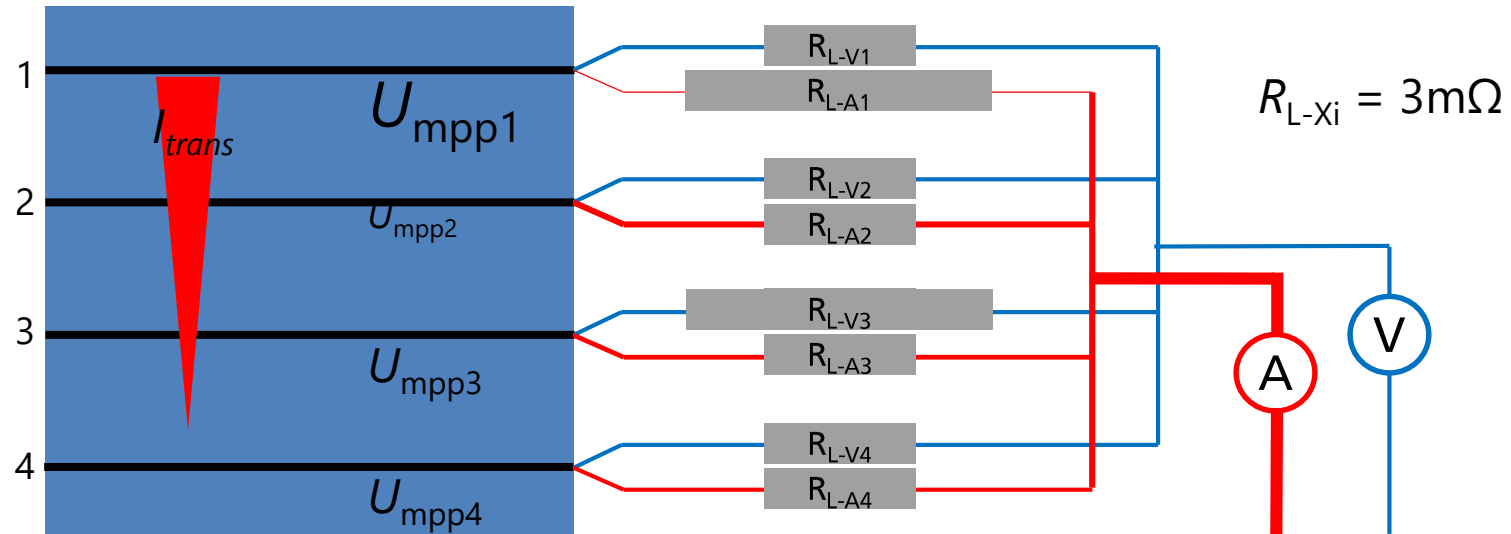
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$R_{L-V1-4}$	LLLL	HLLL	LHLL			
$\Delta U_{mpp} [\%] *$	0.0	-0.26	0.23			

L = 3mΩ, H = 13mΩ

# Nonuniform contact resistance – Analytical model



$$\Delta U_{BB1-2} = I_{trans} * R_{BB1-2}$$

$$R_{L-A1} = 13m\Omega \rightarrow I_{trans} = 0.6A, \Delta U_{BB1-2} = 12 \text{ mV} \text{ für } R_{BB1-2} = 20m\Omega$$

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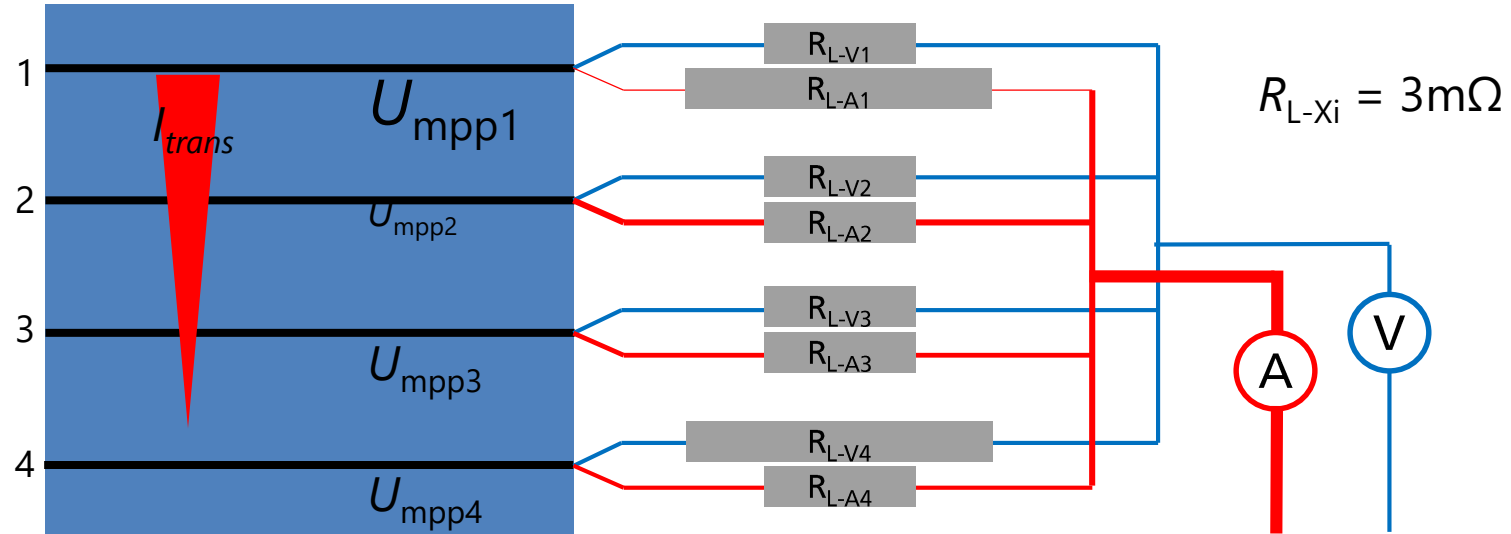
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$R_{L-V1-4}$	LLLL	HLLL	LHLL	LLHL		
$\Delta U_{mpp} [\%] *$	0.0	-0.26	0.23	0.03		

L = 3mΩ, H = 13mΩ

# Nonuniform contact resistance – Analytical model



$$\Delta U_{BB1-2} = I_{trans} * R_{BB1-2}$$

$$R_{L-A1} = 13m\Omega \rightarrow I_{trans} = 0.6A, \Delta U_{BB1-2} = 12 \text{ mV} \text{ für } R_{BB1-2} = 20m\Omega$$

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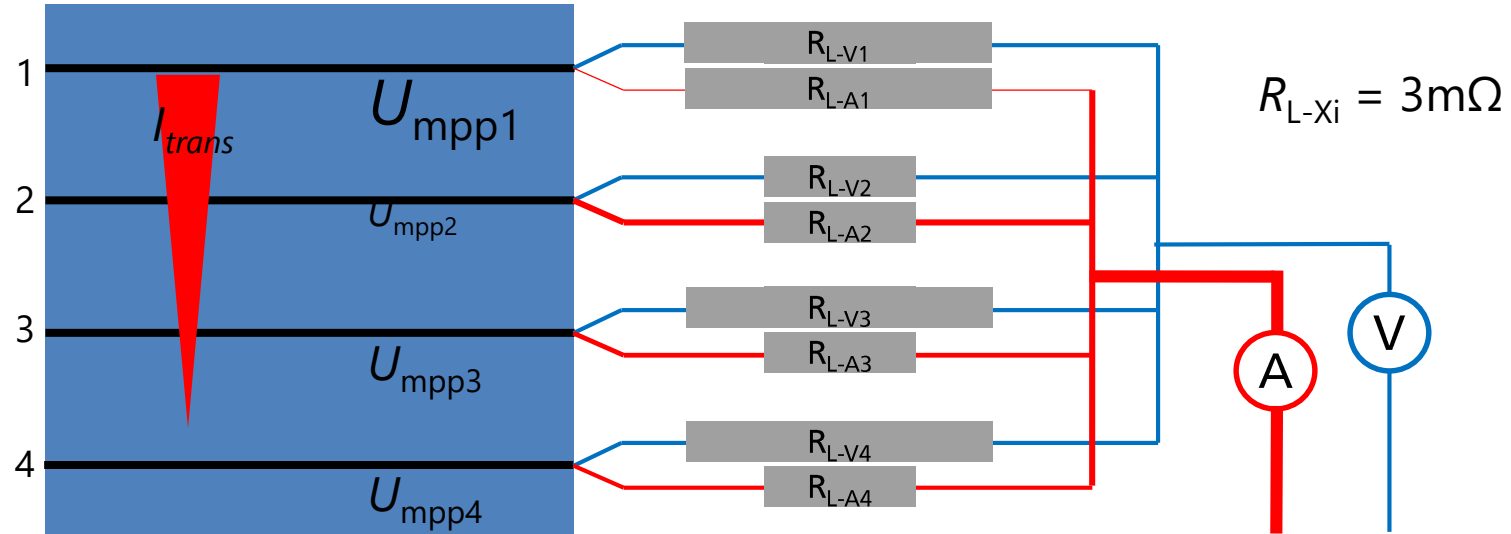
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$R_{L-V1-4}$	LLLL	HLLL	LHLL	LLHL	LLLH	
$\Delta U_{mpp} [\%] *$	0.0	-0.26	0.23	0.03	0.0	

L = 3mΩ, H = 13mΩ

# Nonuniform contact resistance – Analytical model



$$\Delta U_{BB1-2} = I_{trans} * R_{BB1-2}$$

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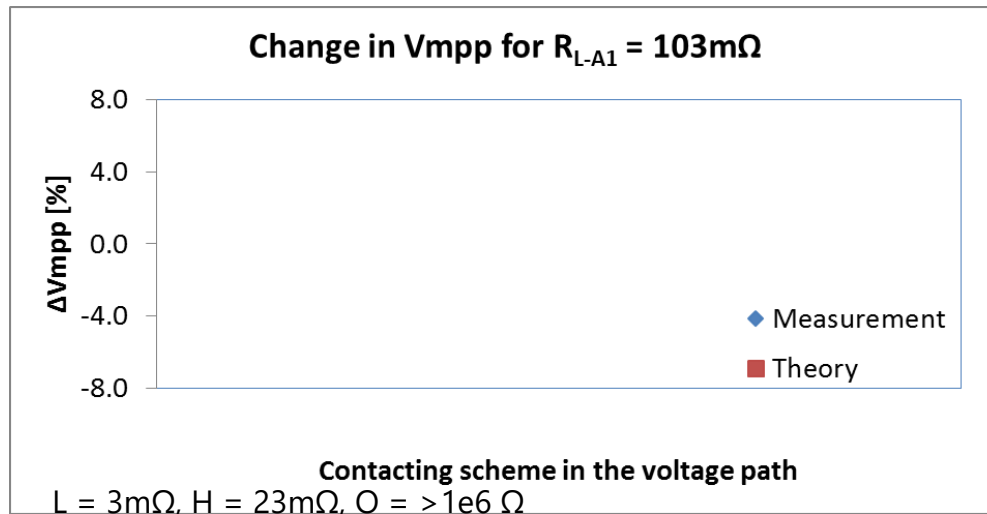
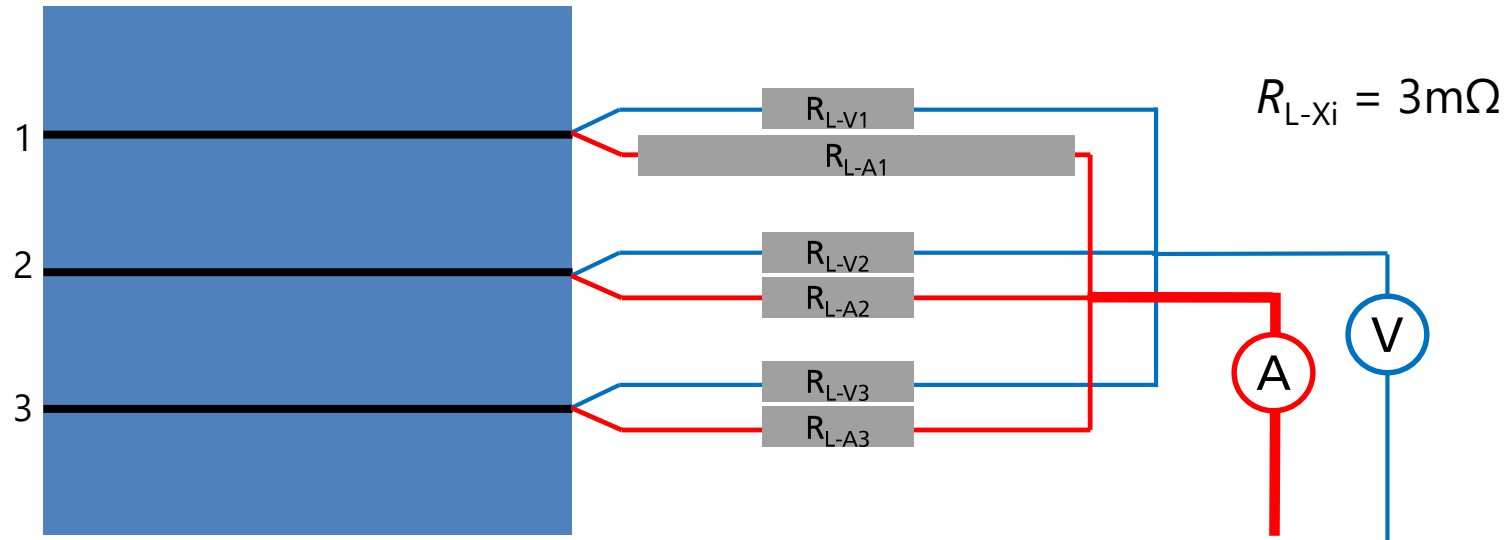
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$R_{L-V1-4}$	LLLL	HLLL	LHLL	LLHL	LLLH	HLHH
$\Delta U_{mpp} [\%] *$	0.0	-0.26	0.23	0.03	0.0	-0.44

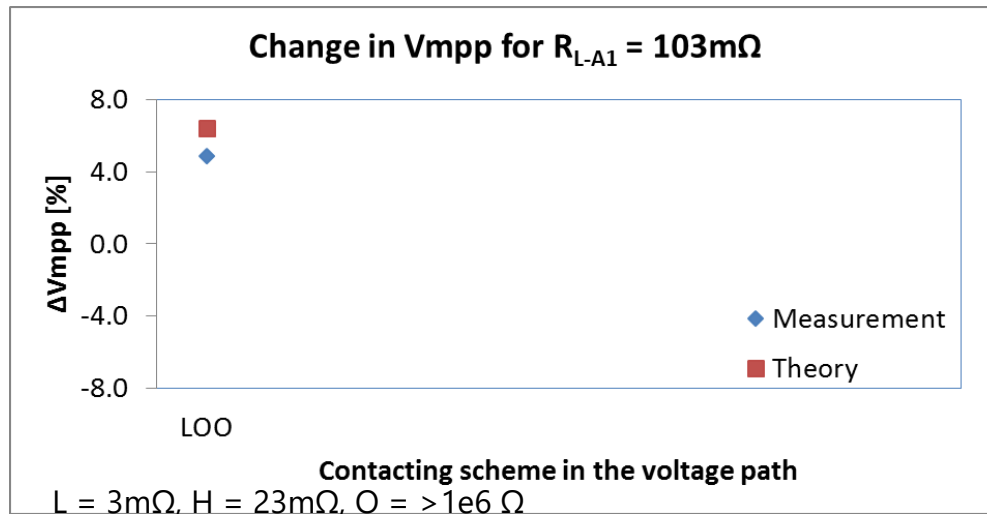
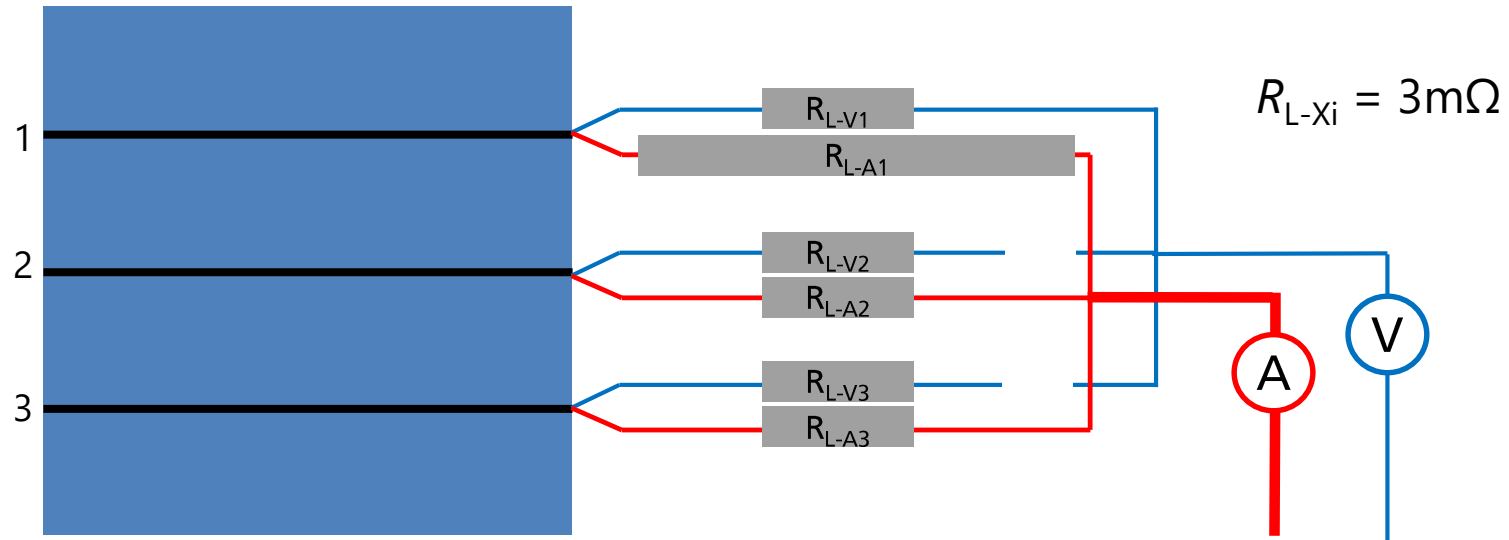
L = 3mΩ, H = 13mΩ

# Nonuniform contact resistance – Experimental verification

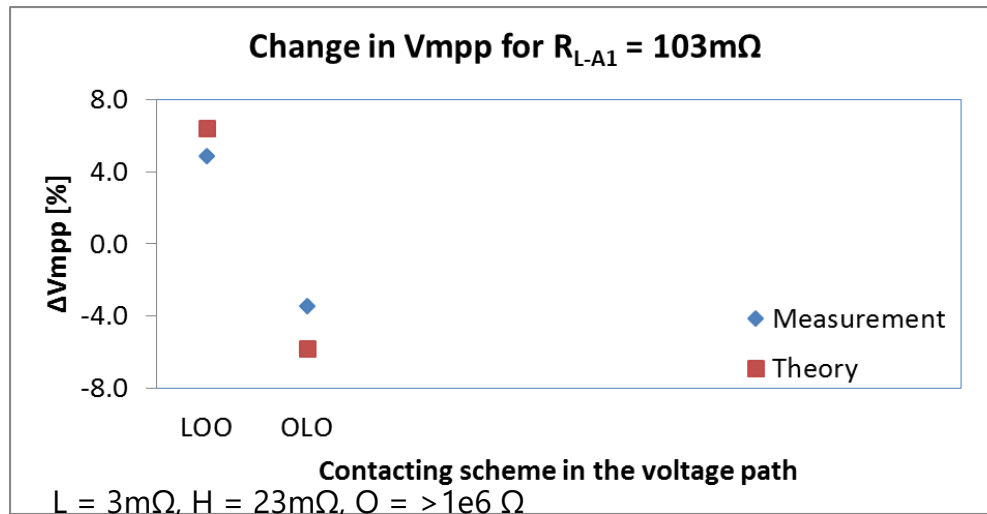
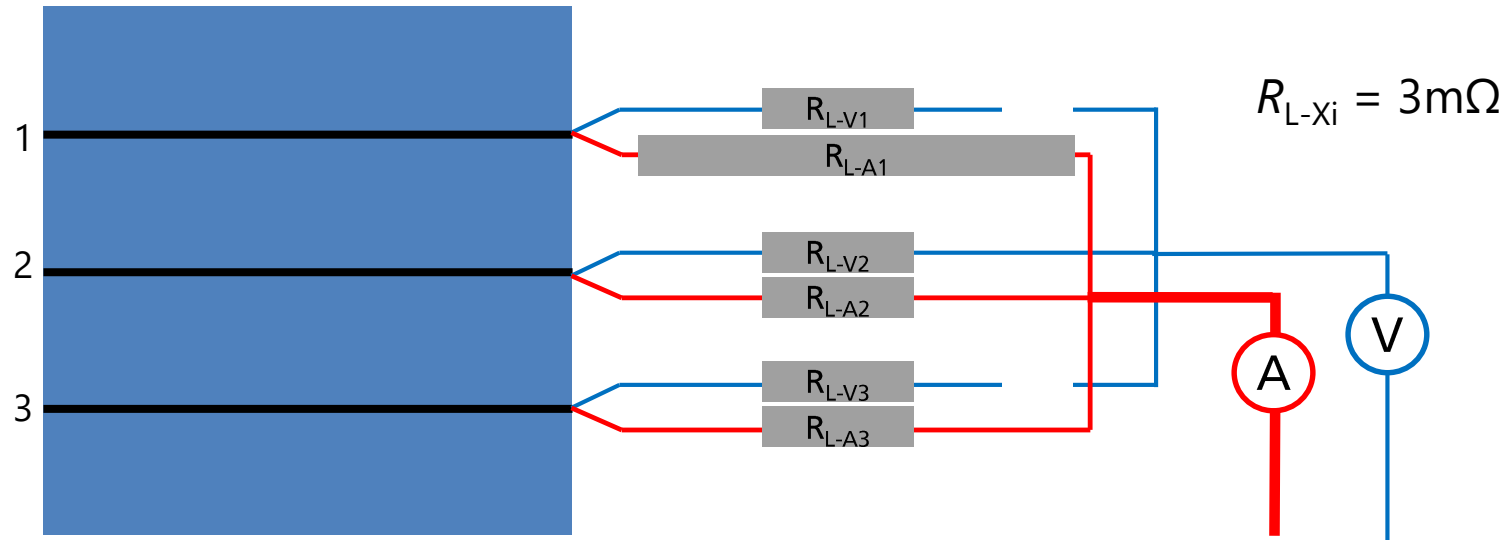




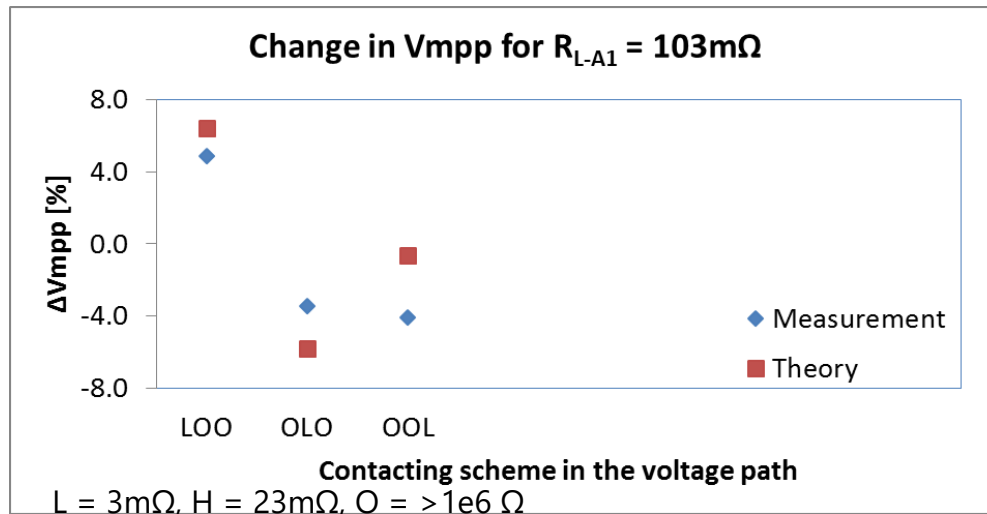
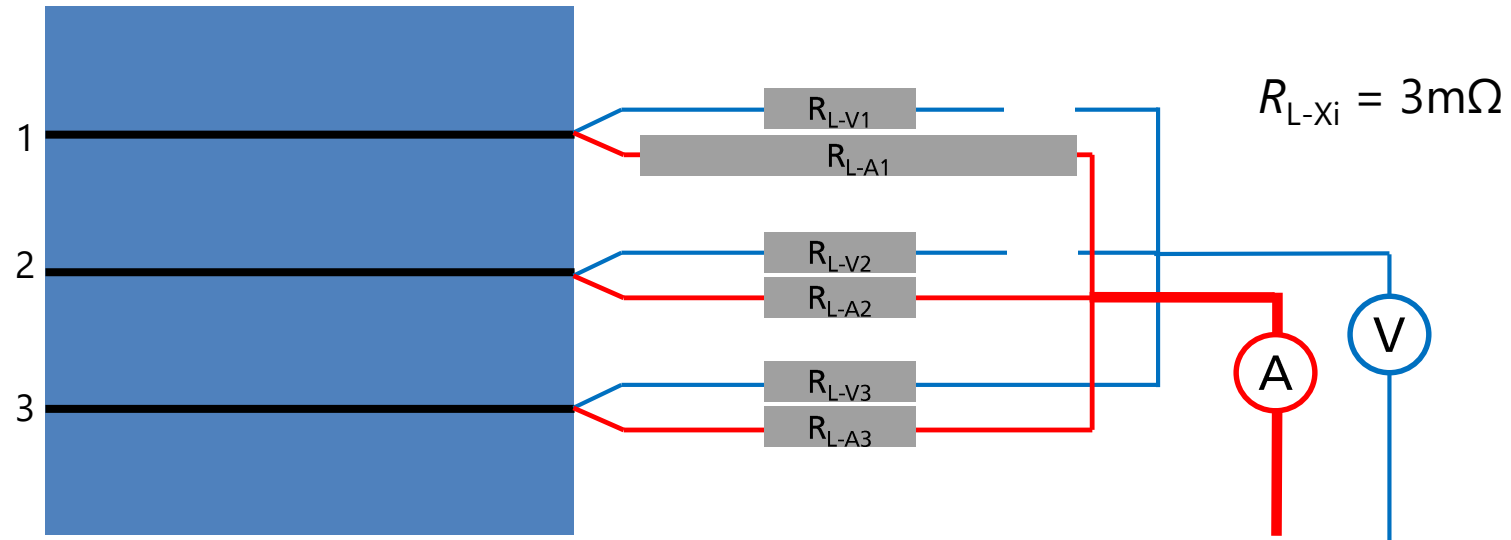
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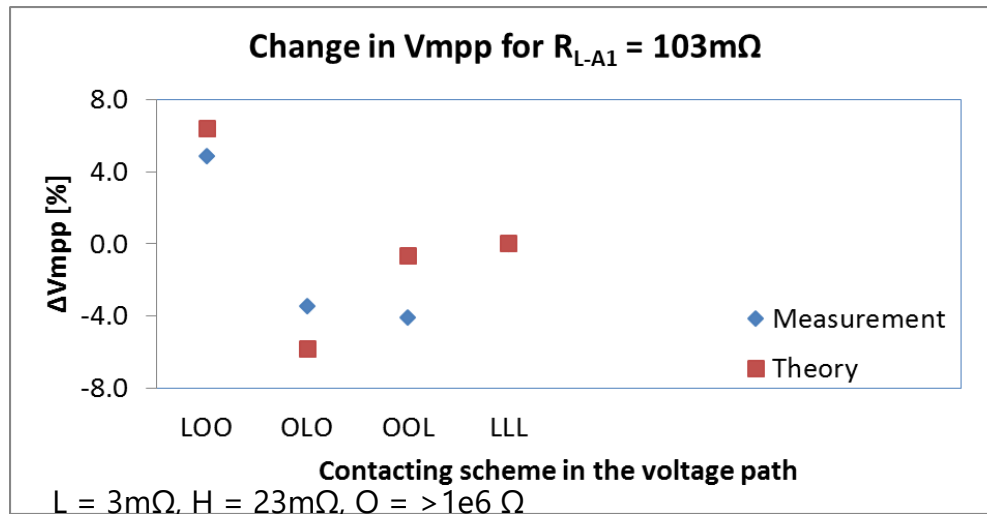
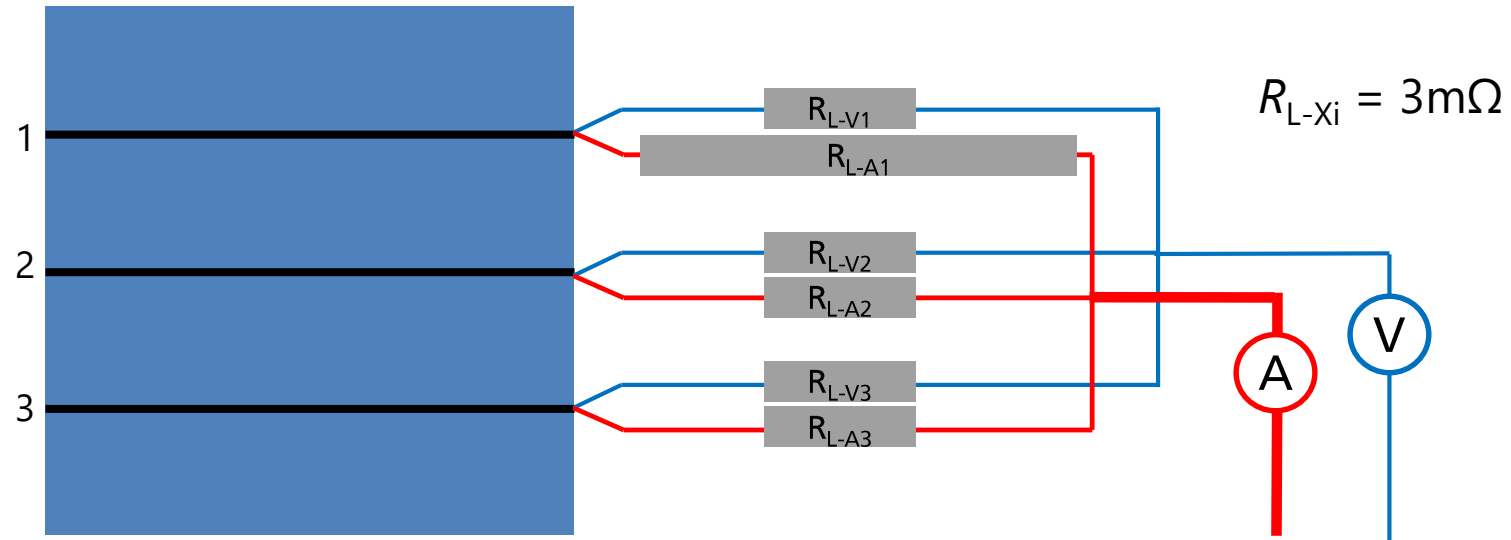
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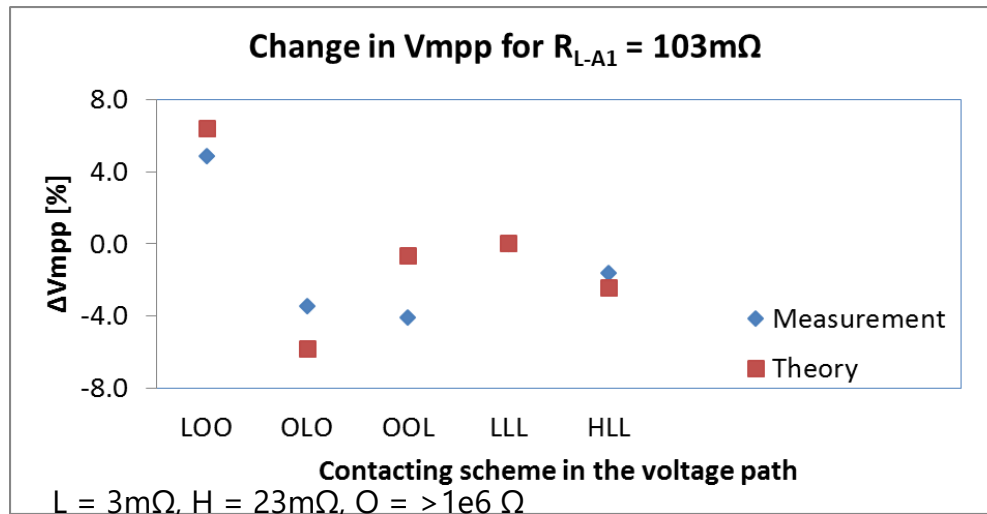
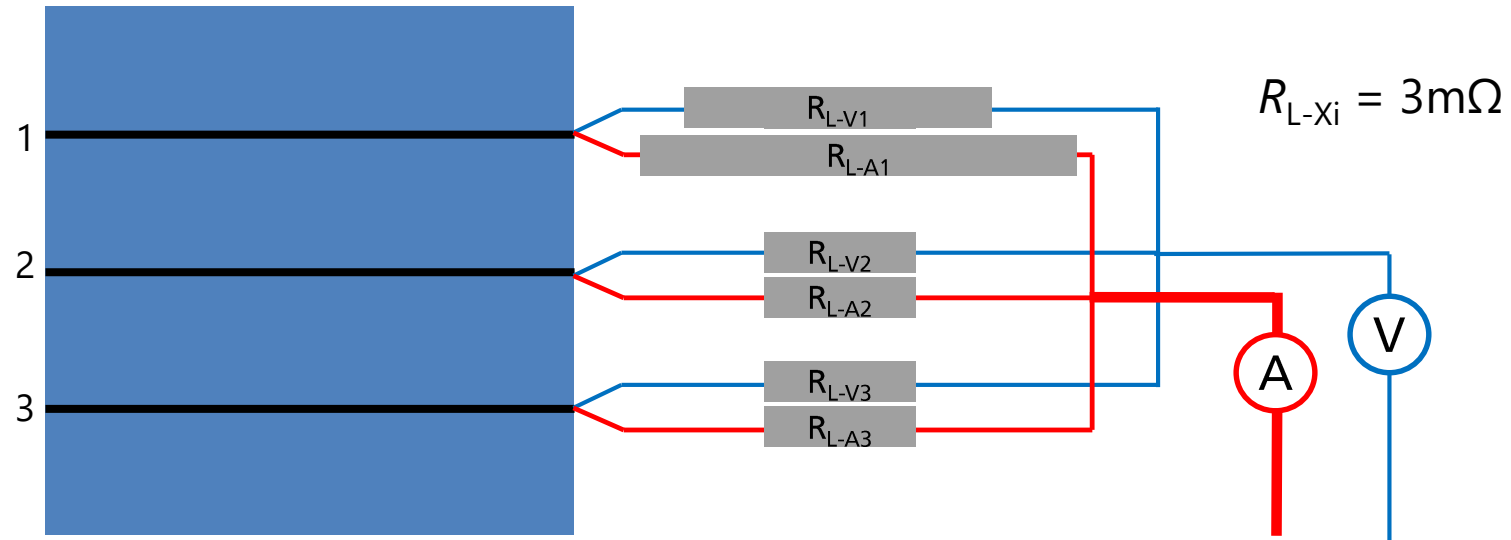
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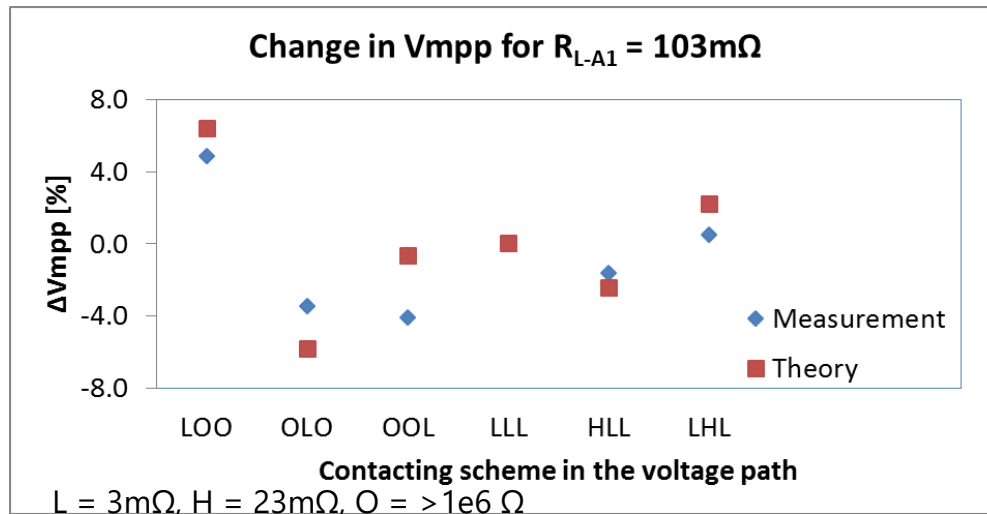
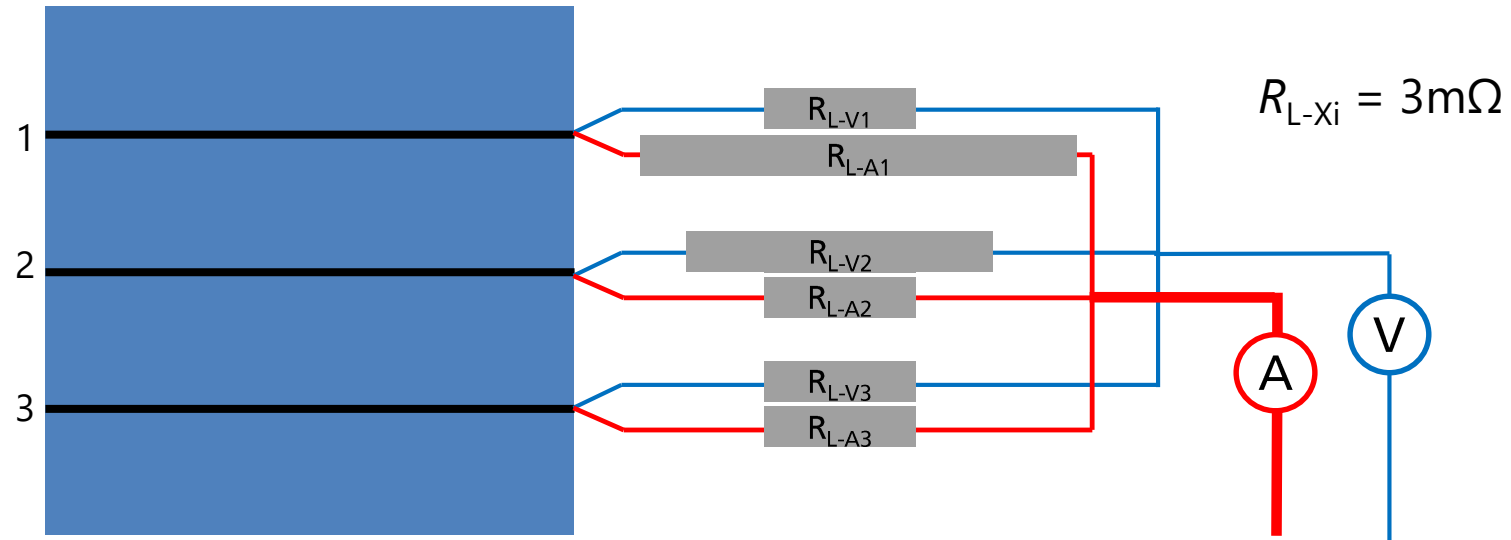
# Nonuniform contact resistance – Experimental verification



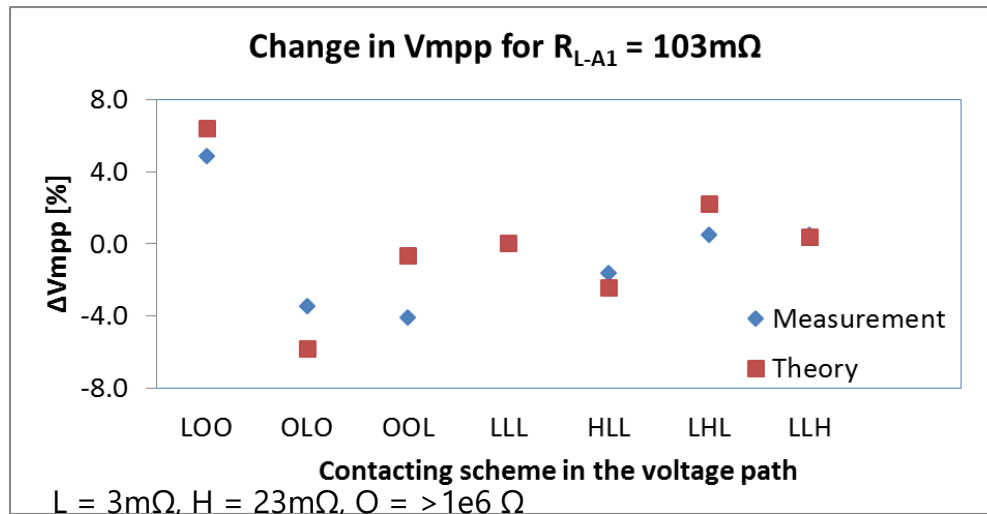
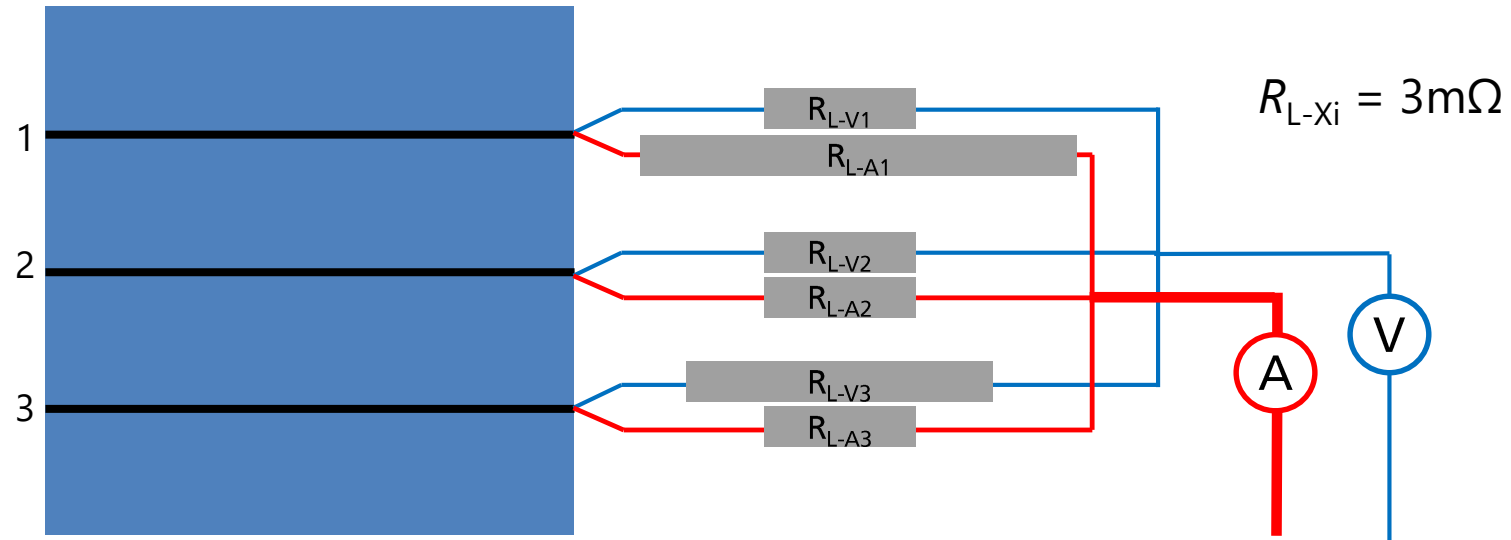
# Nonuniform contact resistance – Experimental verification



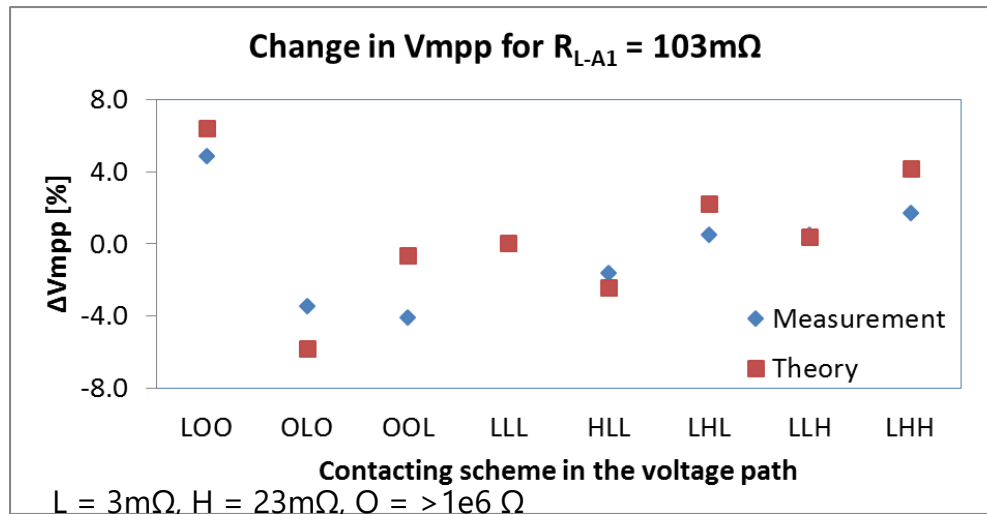
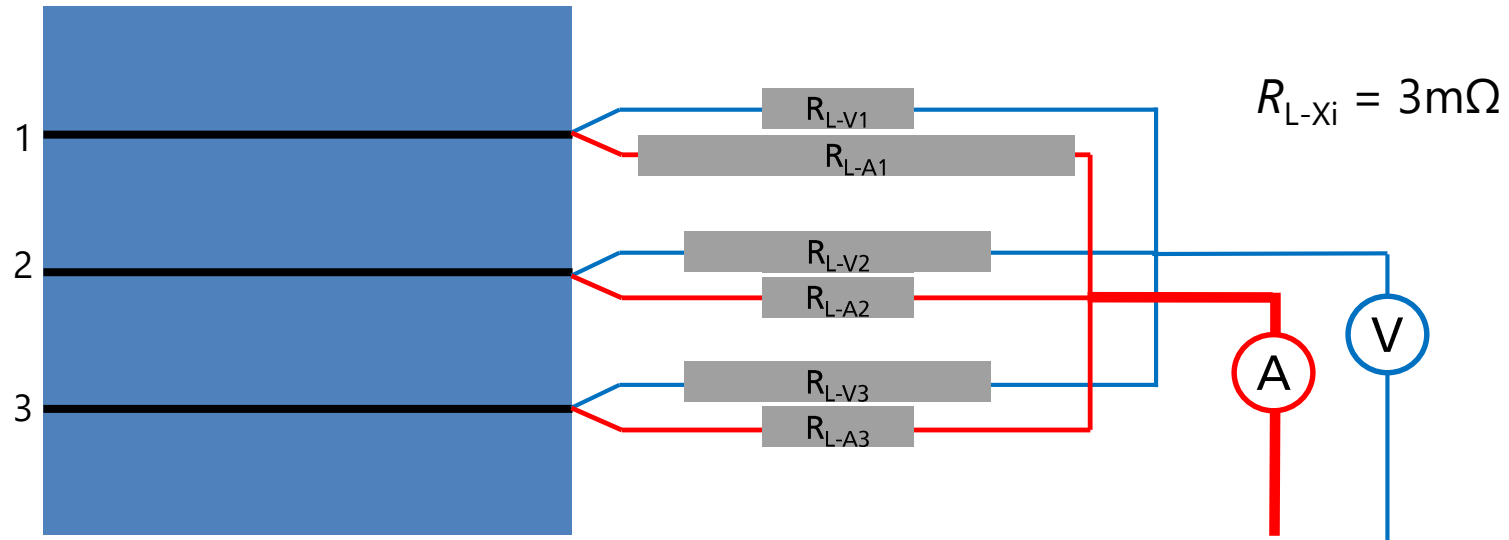
# Nonuniform contact resistance – Experimental verification



# Nonuniform contact resistance – Experimental verification



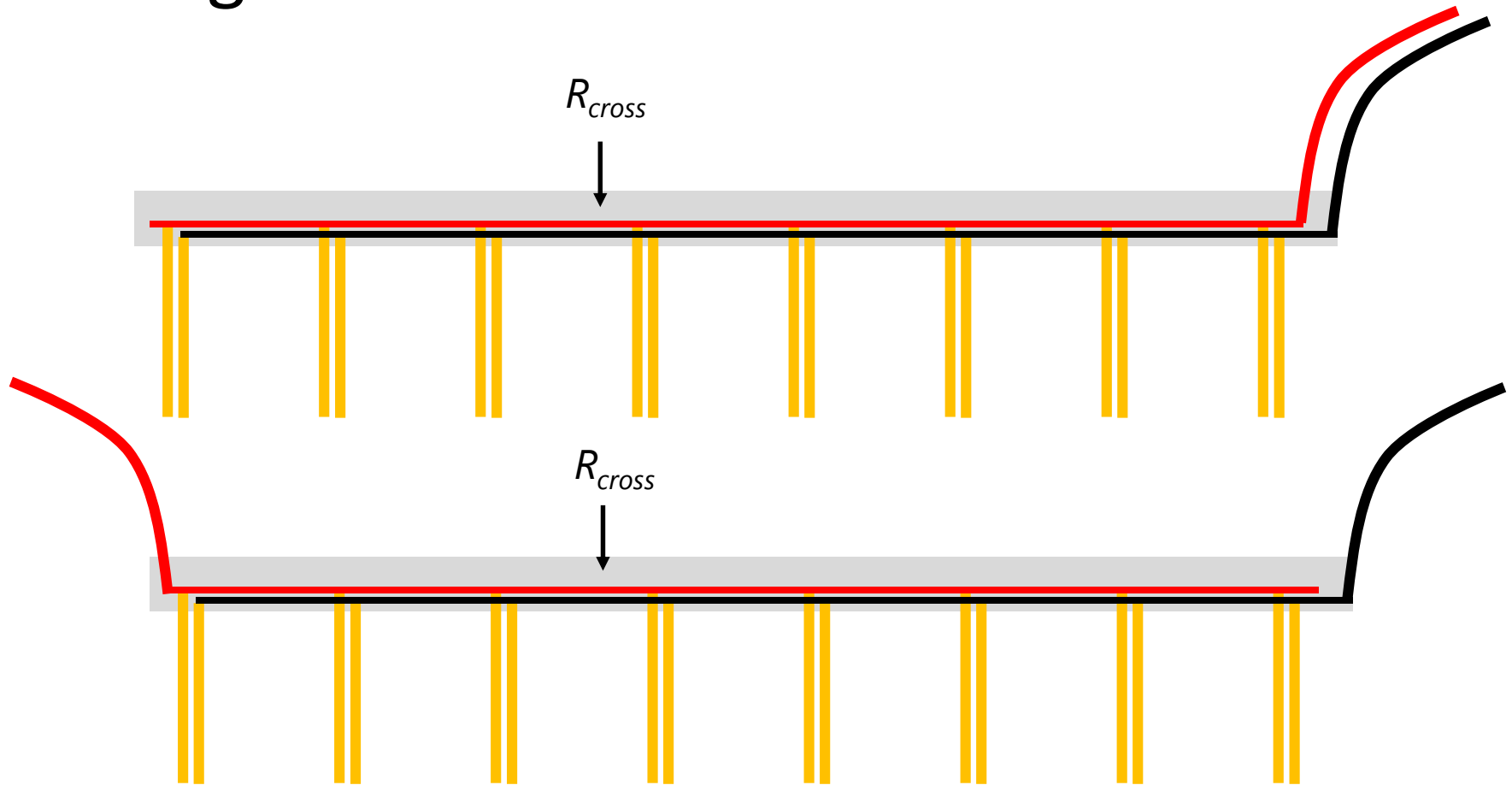
# Nonuniform contact resistance – Experimental verification



- Arbitrary  $FF$  for different contacting resistance possible
- Balanced resistance in the voltage path sufficient to get correct  $FF$



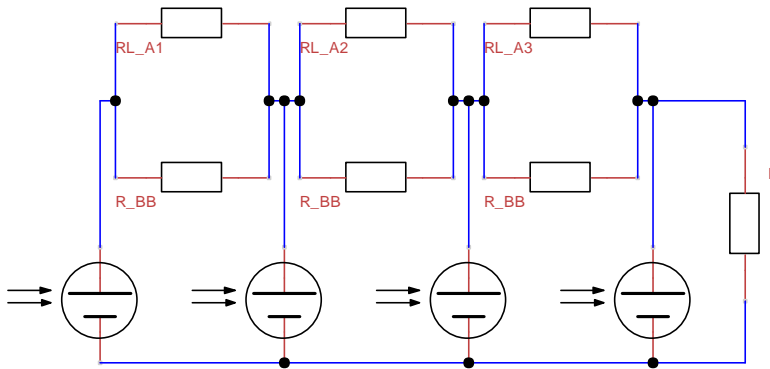
# Design of the contact bar



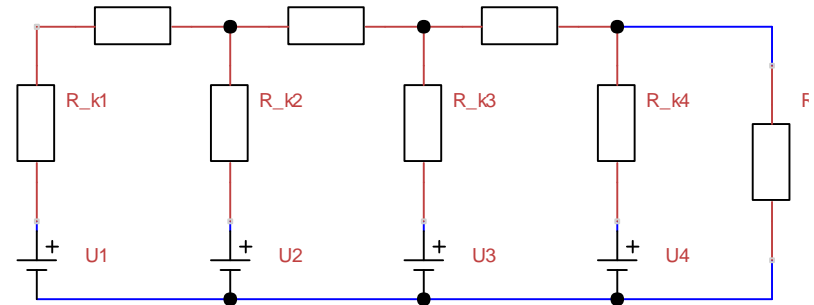
➤ Influence of the resistance of the cross connector?

# Design of the contact bar

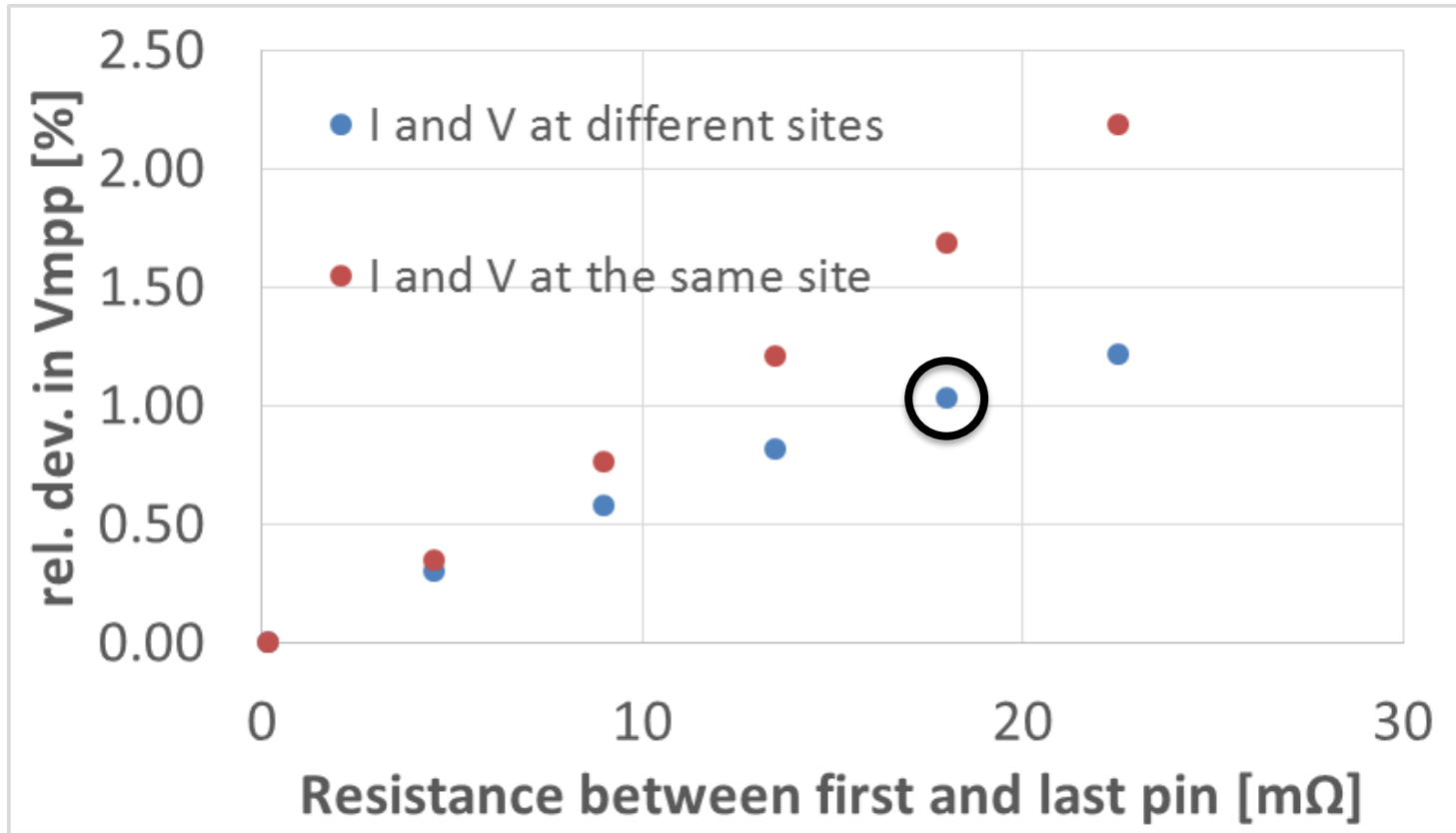
1) Calculate the current flow and resulting voltage drops



2) Calculate  $V_{\text{tot}}$



# Influence of $R_{\text{cross}}$



➤  $R_{\text{cross}}$  can add a significant "gain" in  $FF$

# Conclusion

- Nonuniform contact resistance changes  $FF$  arbitrarily
- Balanced resistance in the voltage path is sufficient
- Use additional resistors in the current path to compensate small differences
- Avoid significant  $R_{\text{cross}}$

